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EGNOS Performance at System CDR

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Alcatel Space Industries

Nav Convention 2002
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Nice (France)

NavSat

2002

Satellite navigation and positioning world show

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Presentation overview

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Introduction

System Performance requirements
System Architecture

Performance Justification Methodology

Methodology
Tools

CPF CDR main performance results

System CDR main performance results

Conclusion



Introduction

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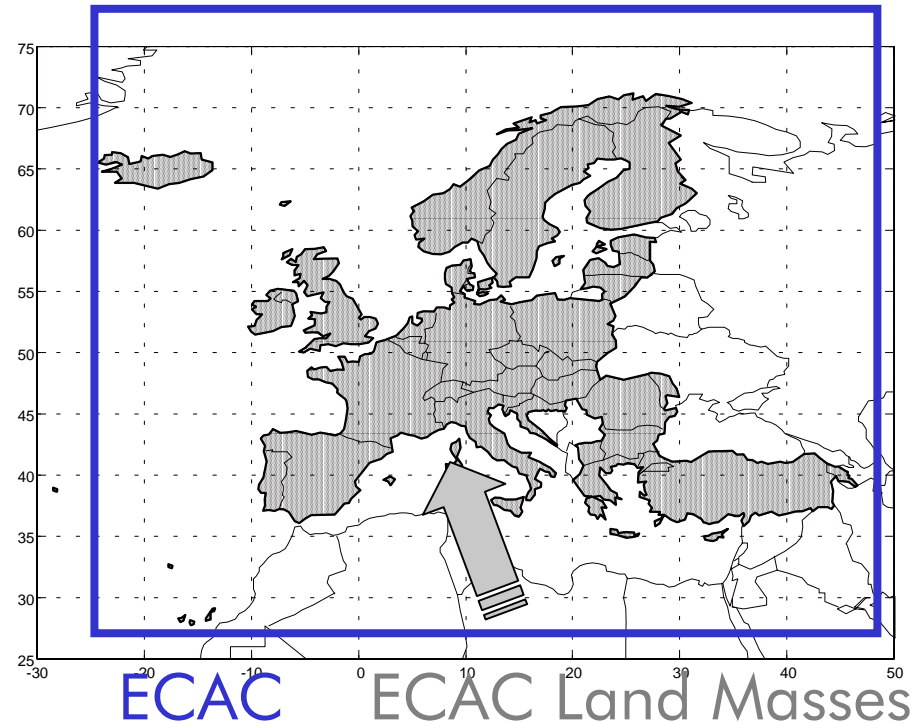
- In April 2002 EGNOS has passed its Critical Design Review
- A key element of this review was the justification of system performance foreseen to be achieved at this stage of the project.
- Indeed some requirements are expressed with very low probabilities (Integrity and Continuity) and demands special care
- Relevant methodology had to be put in place together with the adapted tools to support it



Introduction - Performance

- EGNOS Performance requirement can be split into 4 categories which are Accuracy, Integrity, Continuity and Availability to be met on a specific service area

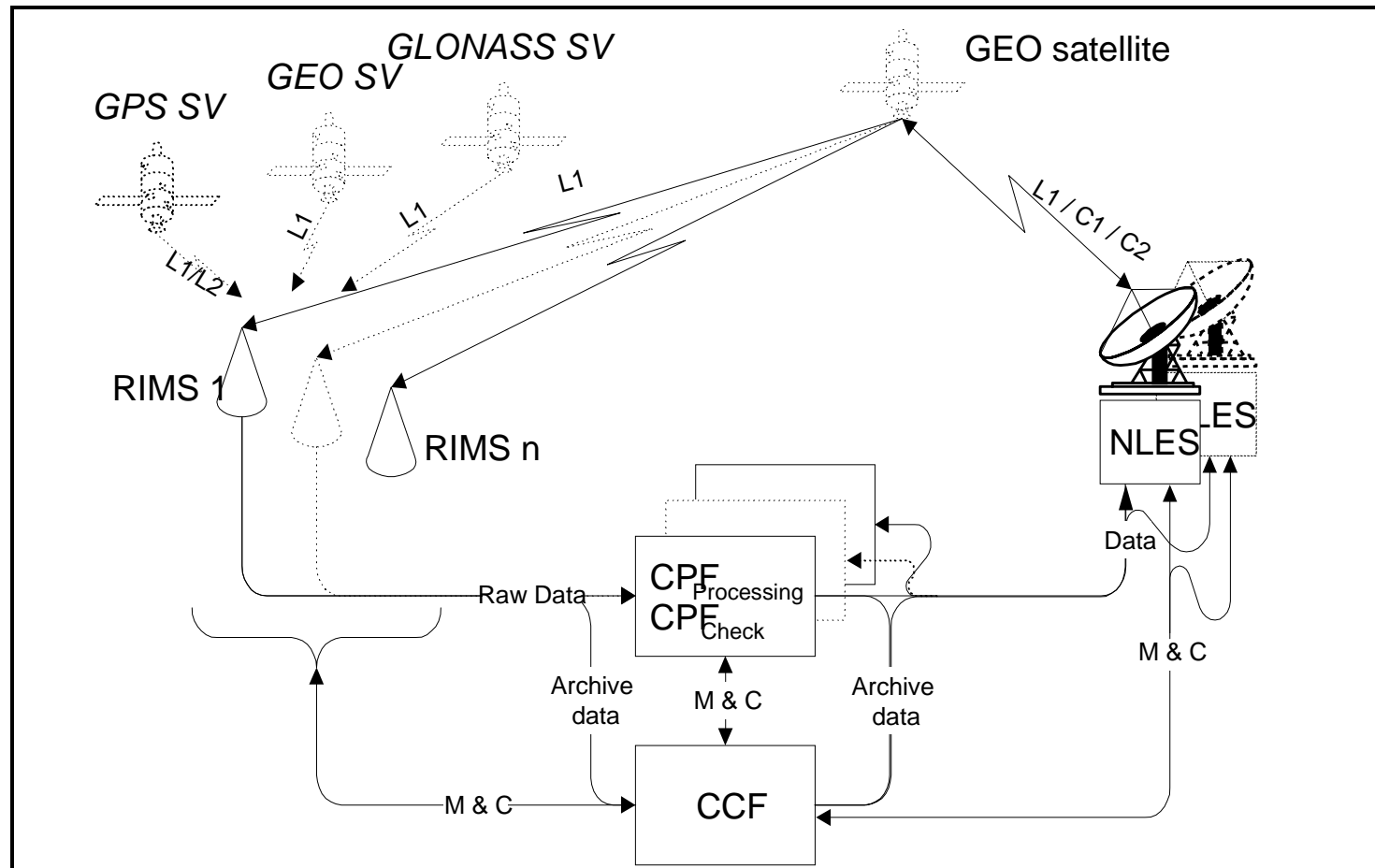
EGNOS AOC SYSTEM REQUIREMENTS	Level 2 (wo Iono corrections)	Level 3A (with all corrections including Iono)
XNSE 95%	100 m (H)	7.7 m (V) 7.7m (H)
Protected Alert Limit	556m (H)	20 m (V) 20 m (H)
Integrity Risk	$10^{-7}/h$	$2.10^{-7}/appr.$
Time to alert (2)	10 s	6 s
Continuity risk Navigation Service	$10^{-5}/h$	$8.10^{-5}/appr.$
Availability	0.999	0.95 (Objective 0.99)
Service Area	ECAC	ECAC land masses



Introduction- Architecture

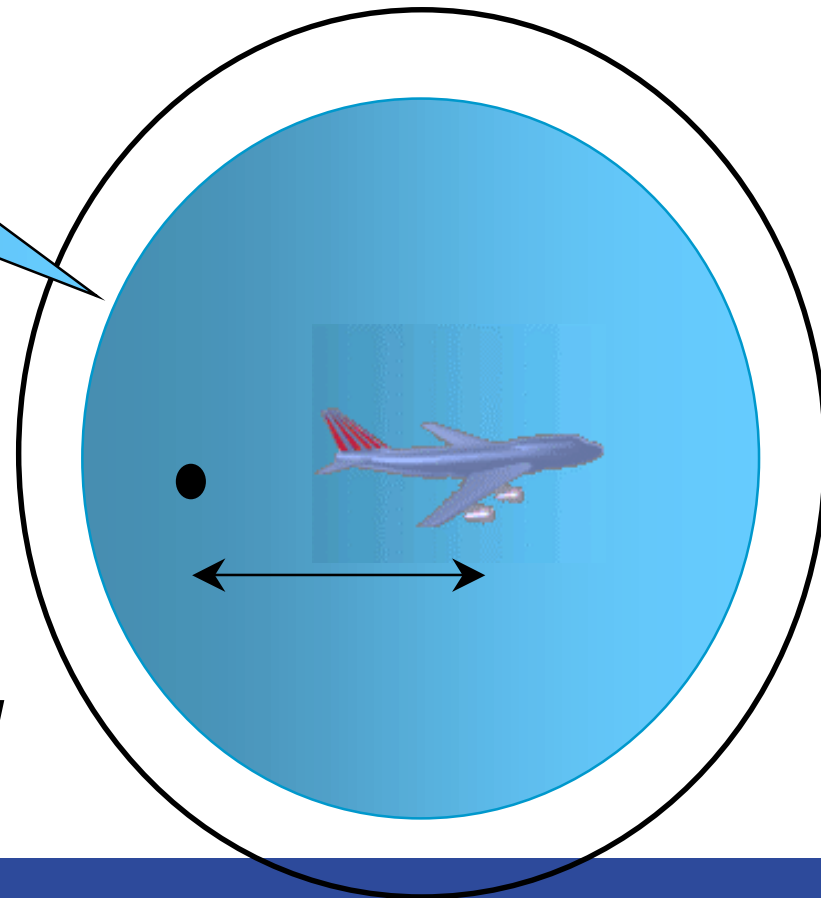
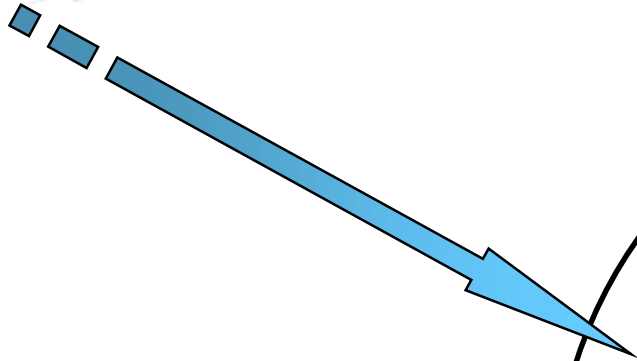
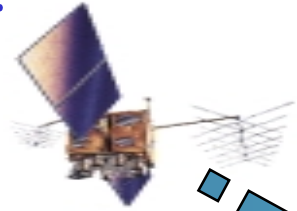
EGNOS Performance relies first on a robust architecture

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Justification Methodology - Accuracy

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True Position →

The **Accuracy** is the
“the error between true
position and the estimated
one”



Justification Methodology - Accuracy

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- **Accuracy expressed as a 95% statistics**

*Only nominal behaviour affects such type of figure
Low event probability are drown in the statistics*

- Accuracy is quantified under **nominal conditions** in terms of:

- RIMS Environment

Return from site surveys to define noise, multipath and interference levels

- Ionosphere Conditions

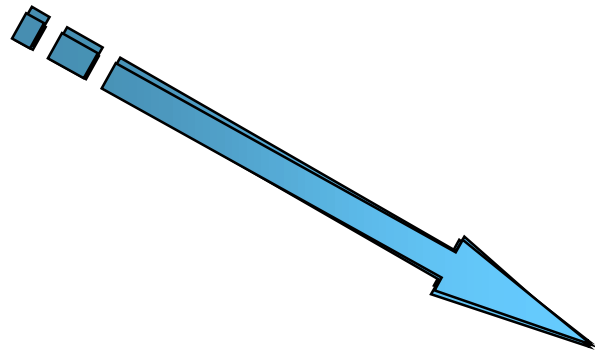
Provided by ESA with the support of Ionosphere European expert (IET)

- Satellite constellation

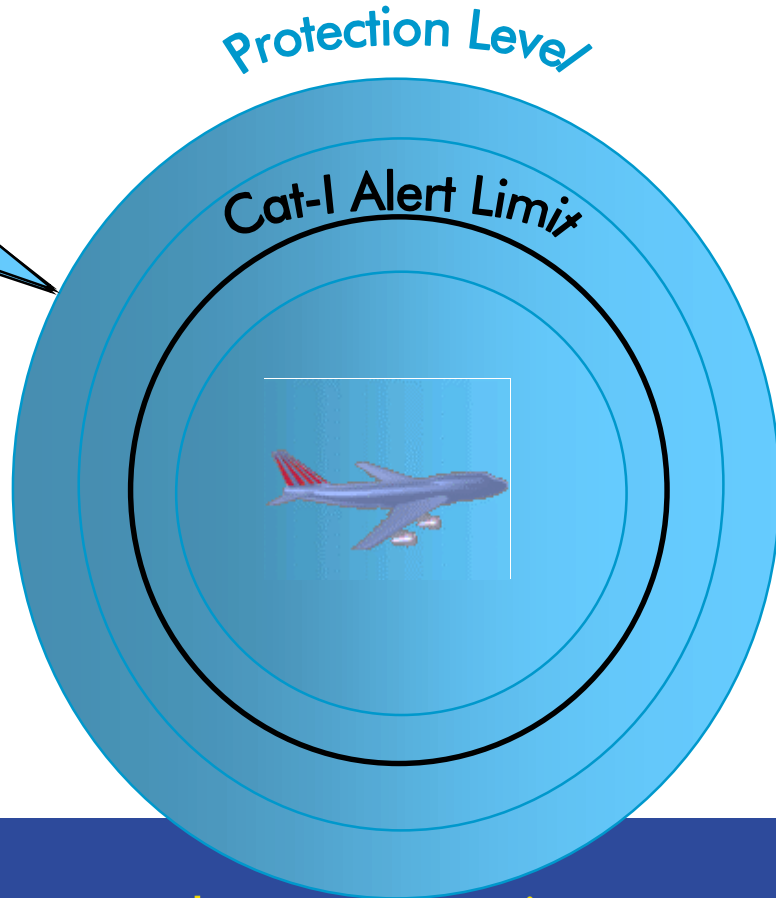
Nominal MOPS constellation (no failure)

Justification Methodology - Availability

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XPL **Yes**
Available:





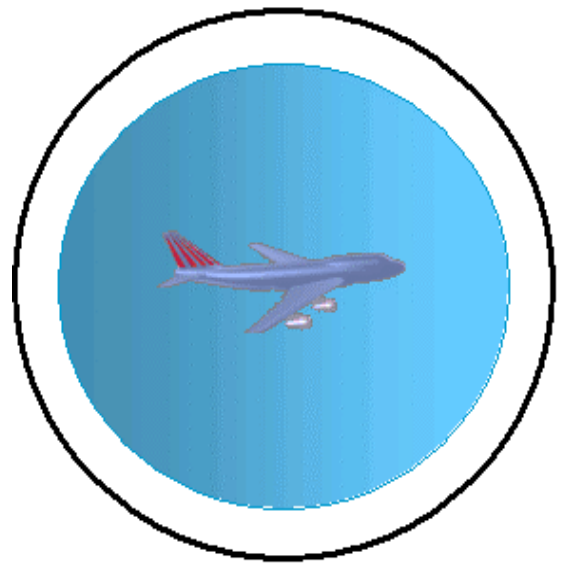
Justification Methodology - Availability

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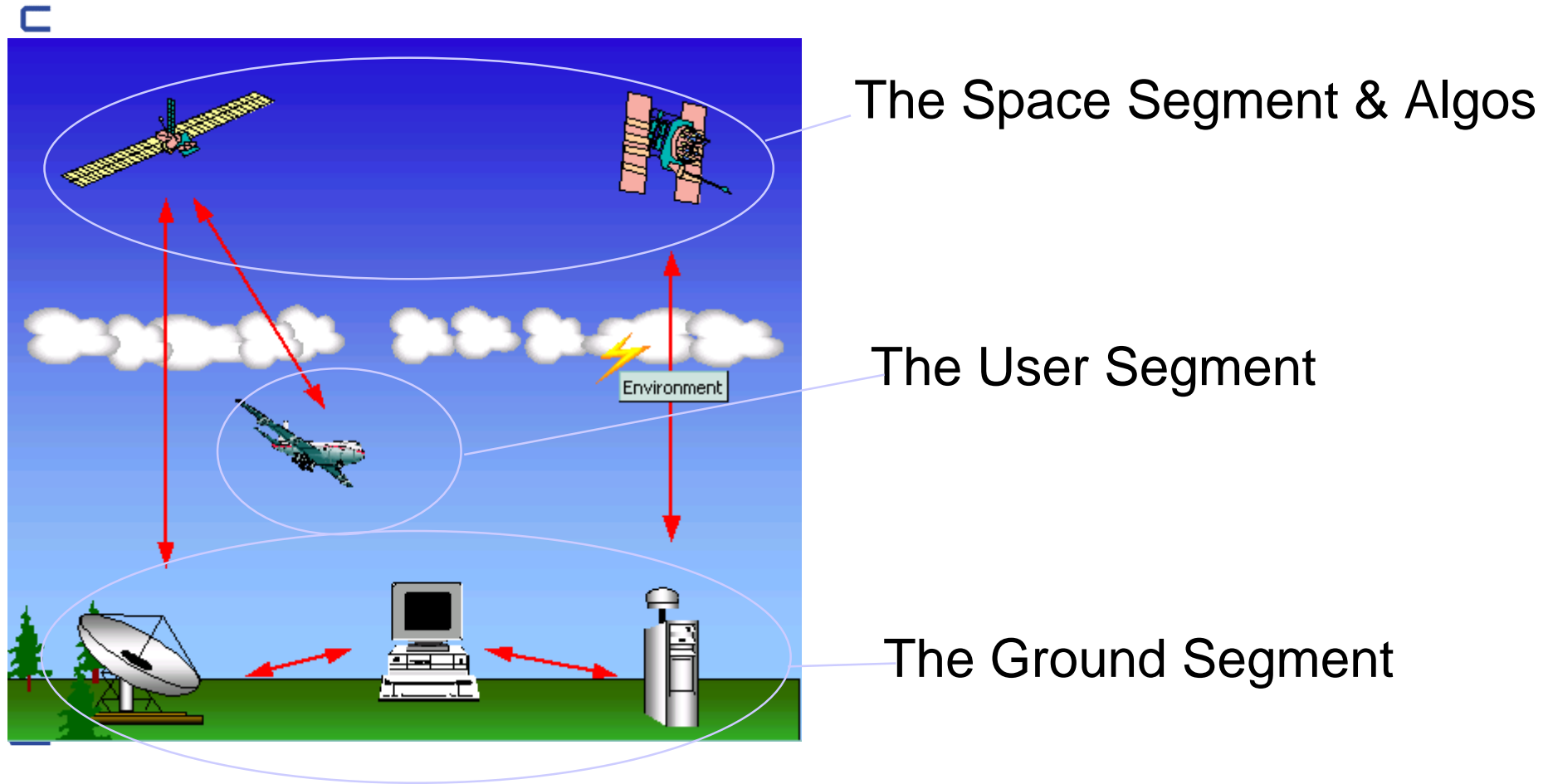
XPL Available: **Yes**

The **XPL Availability** is thus
*“the proportion of time where
the Protection Level is below
the Alert Limit”*





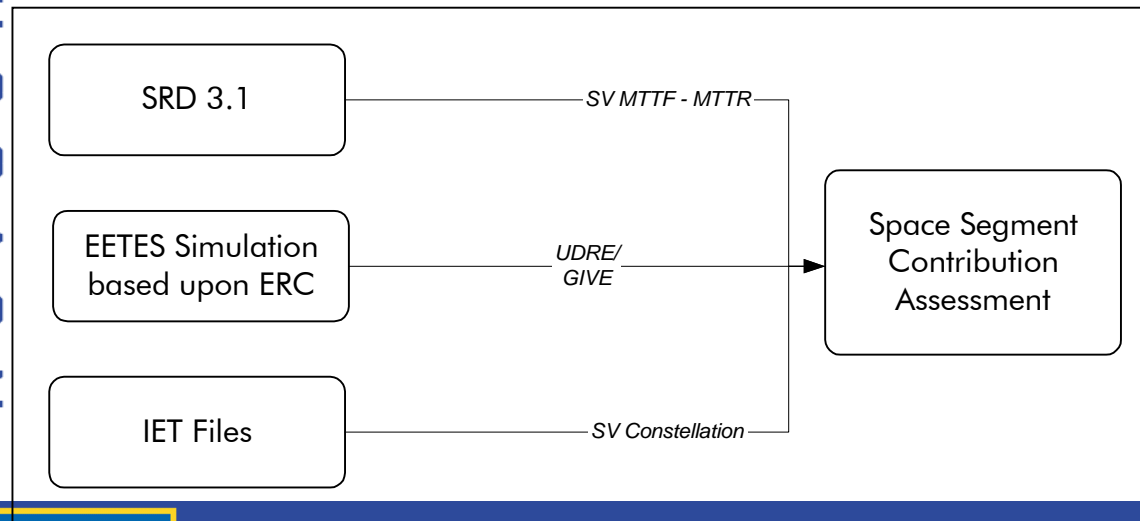
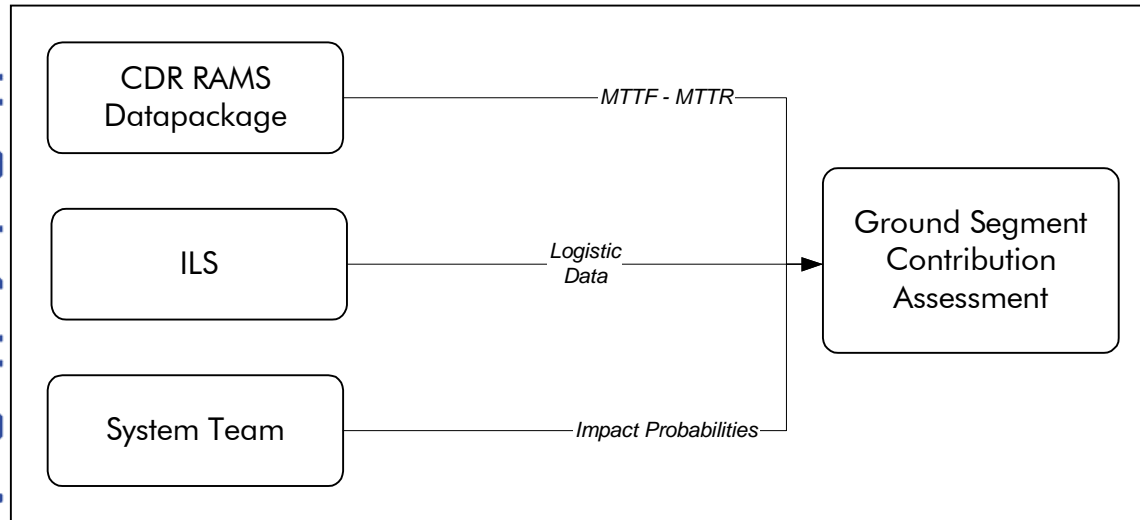
Justification Methodology - Availability





Justification Methodology - Availability

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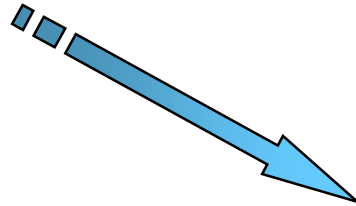


- Ground Segment Contribution
- Space Segment Contribution
- User segment contribution is based on applicable budgets defined in the MOPS



Justification Methodology - Continuity

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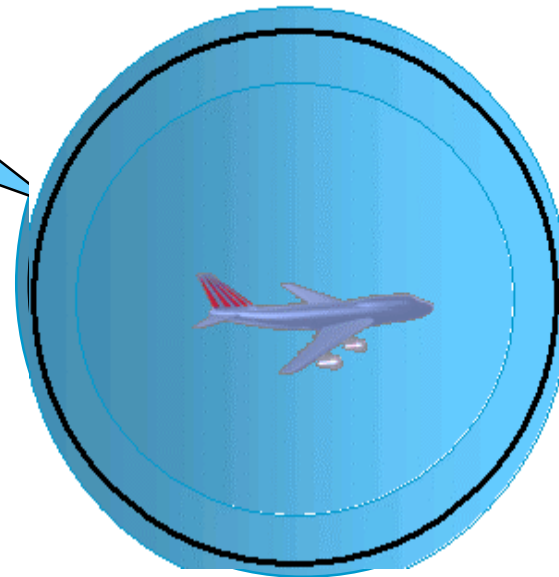
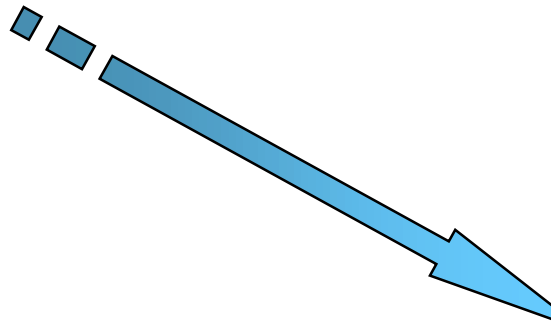


XPL Available: **Yes**

Justification Methodology - Continuity

XPL Available: **No**

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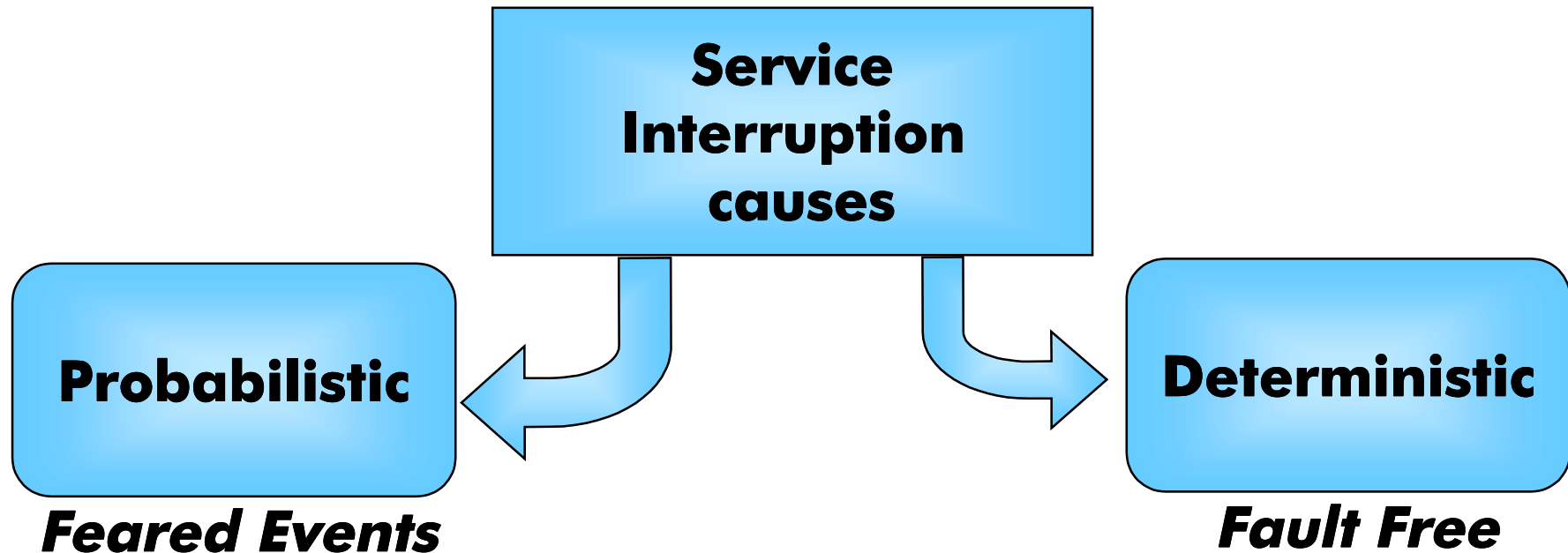


The **Continuity** is thus
*“the system remains
available during the entire
phase of flight”*

Justification Methodology - Continuity

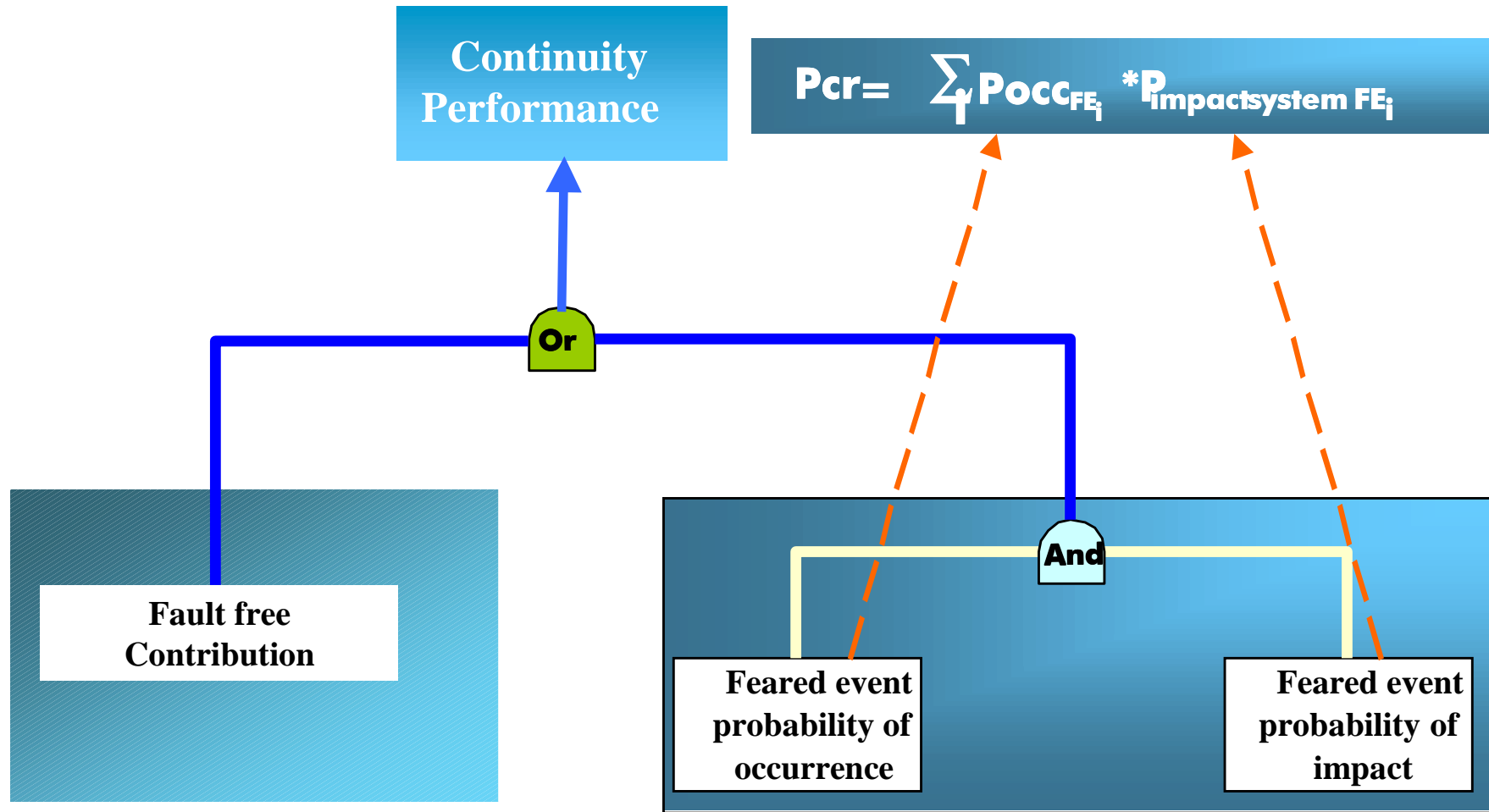
- Requirement expressed with very low probability
Service Level 2: 10^{-5} per hour
- Necessity to refine the models to include impact of low occurrence probability events (so called Feared Events)

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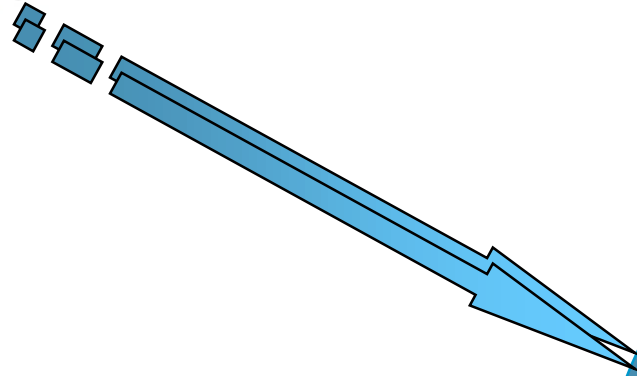
Justification Methodology - Continuity

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Justification Methodology - Integrity

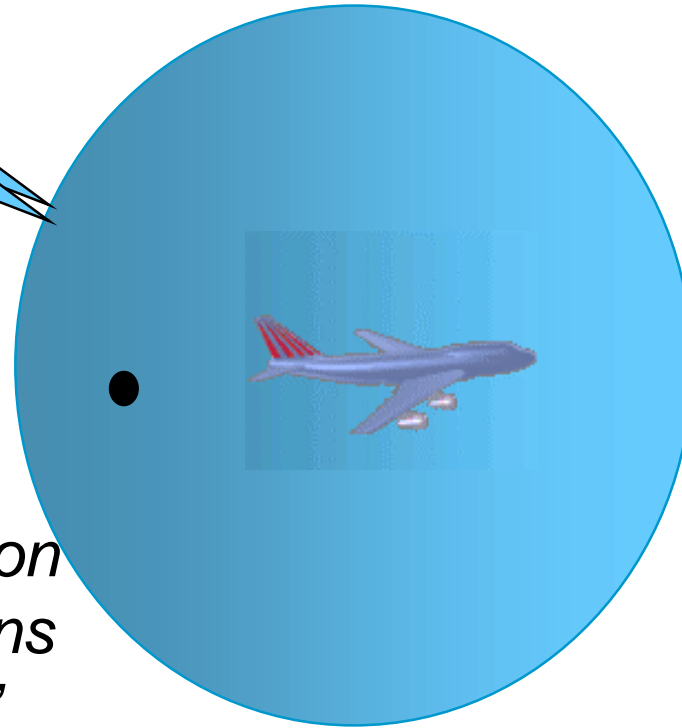
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Integrity:

NOKOK

True Position → ●



The **Integrity** is thus
“the error between true position
and the estimated one remains
within the Protection Level”



Justification Methodology - Integrity

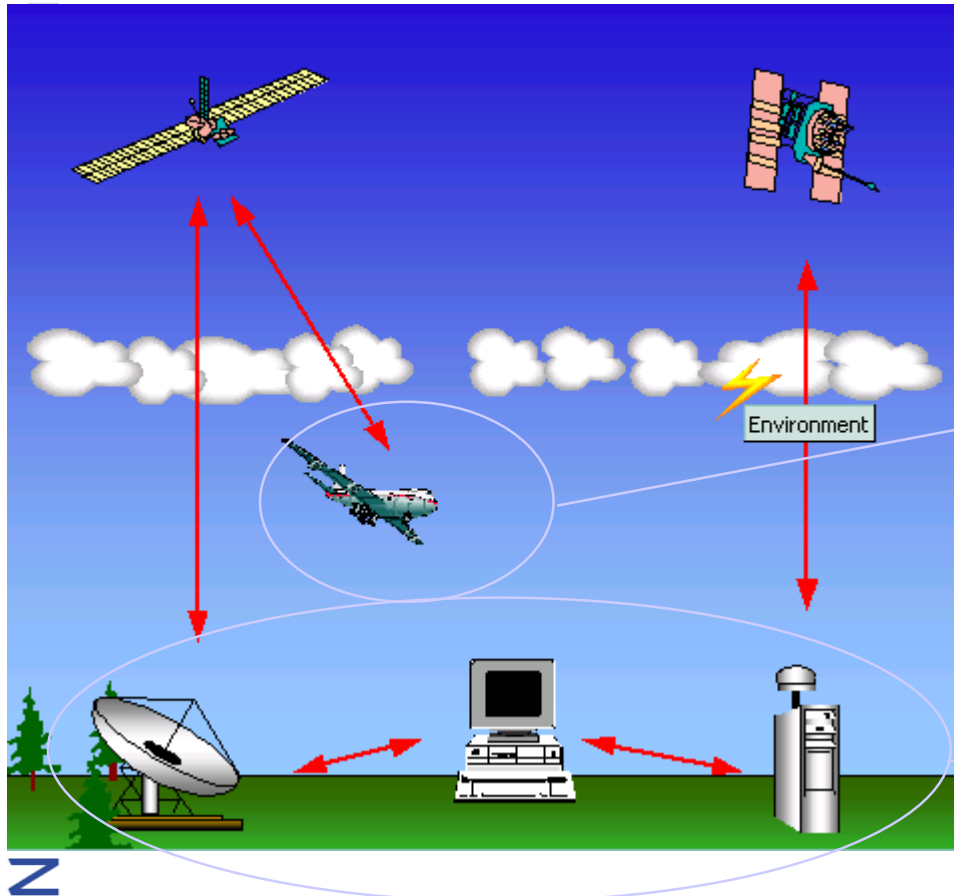
Conservative Approach

- **Pseudo-range to position domain transfer**
 - integrity is assessed in the pseudo-range domain (i.e. integrity of the CPF Output)
 - This is a very conservative approach
 - * System Impact probability selected = 100%
 - * Estimation showed that System Impact is in between 0.4% and 4%
- **CPF anticipated models are more conservative than the simulations results**
- **Anticipated Occurrence Probabilities are more conservative than estimation with Real Data**

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Simulation Tools



Petri Net - FTA - FMECA
(RAMS Tool)

EGNOS Service Volume Simulator
(ESVS)

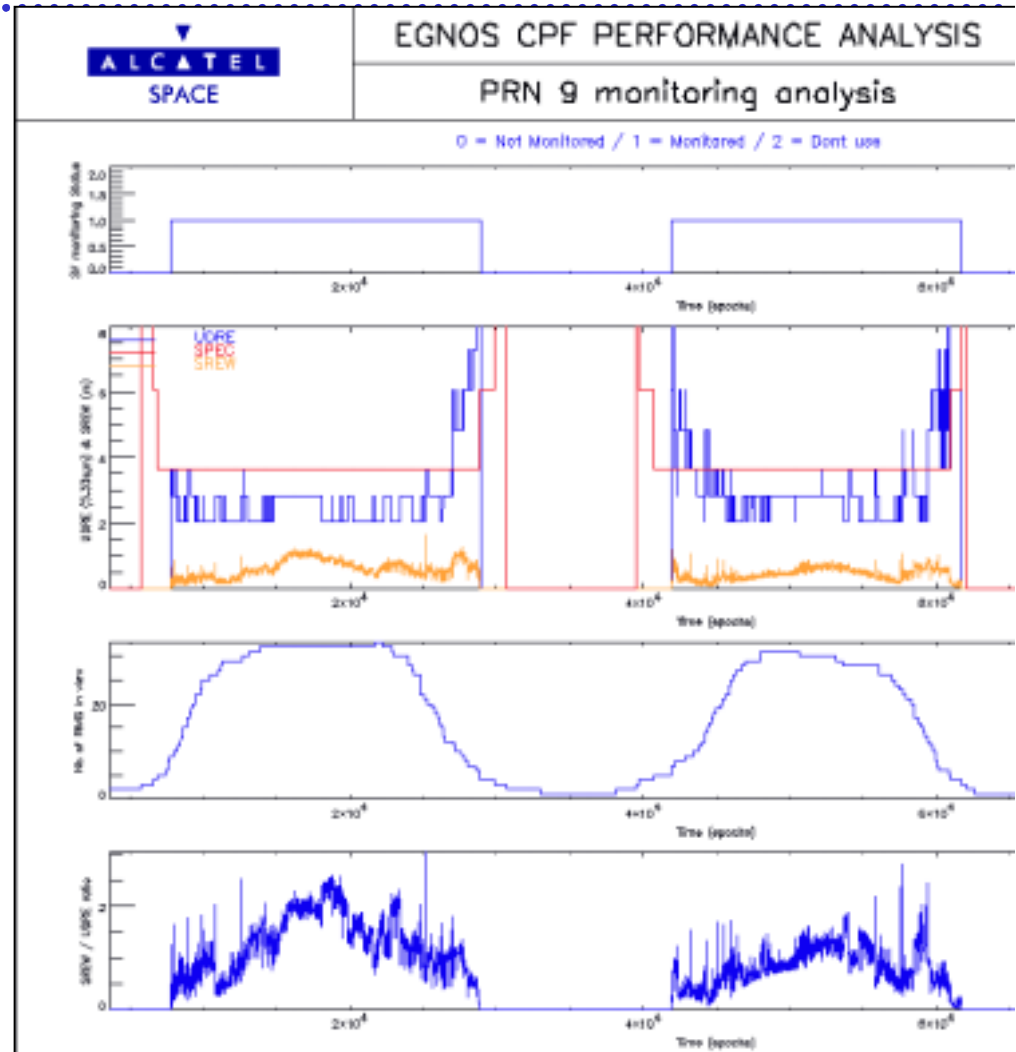
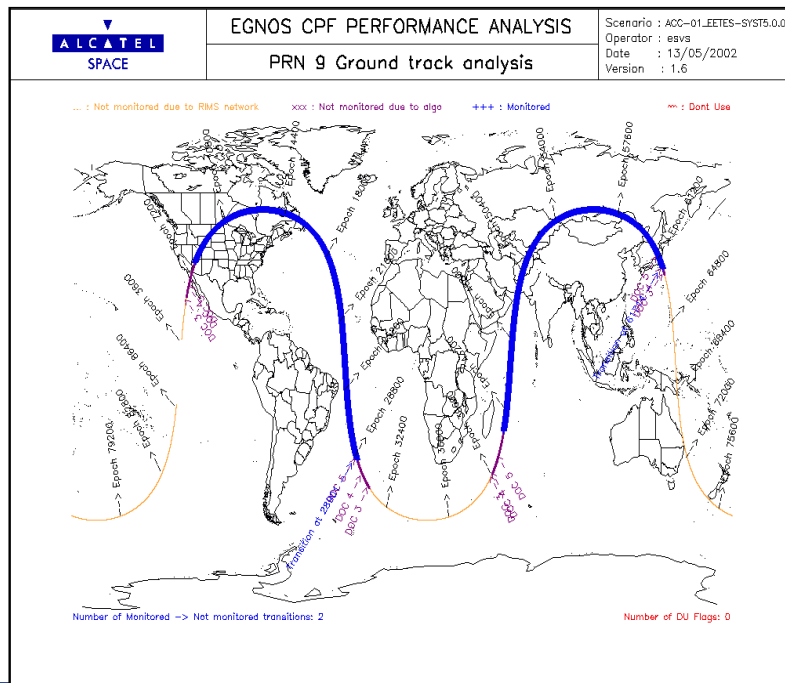
EGNOS End to End Simulator
(EETES)



CPF CDR Main Outcomes

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CPF Satellite Monitoring Capability PRN09 Example



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Satellite navigation and positioning world show

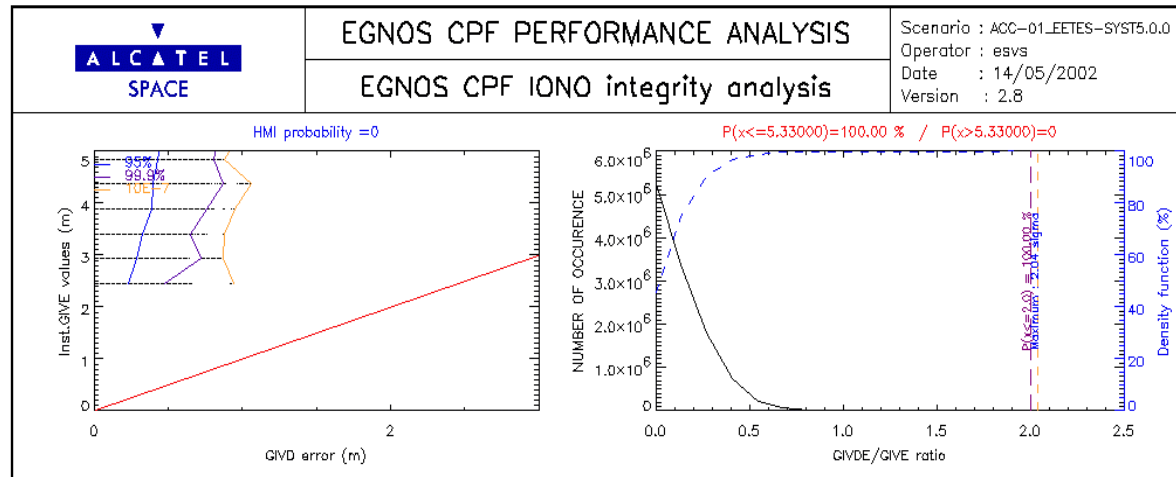


CPF CDR Main Outcomes

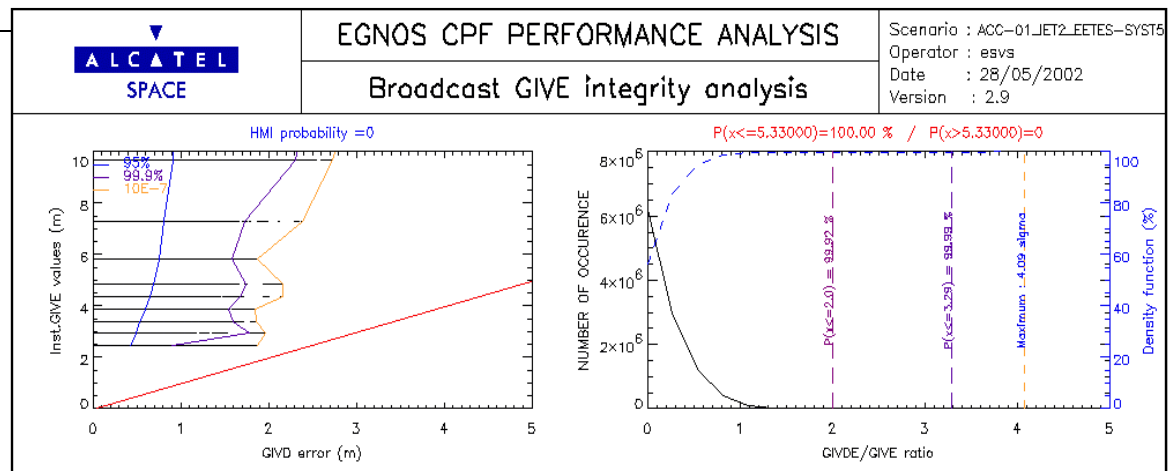
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CPF GIVE Integrity Capability

Nominal Conditions
Large Margins



Extreme Conditions
Margins Reduced
but bounding
capabilities
maintained





CPF CDR Main Outcomes

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Compliance to Message MOPS Specifications
The Message is what is used by the system

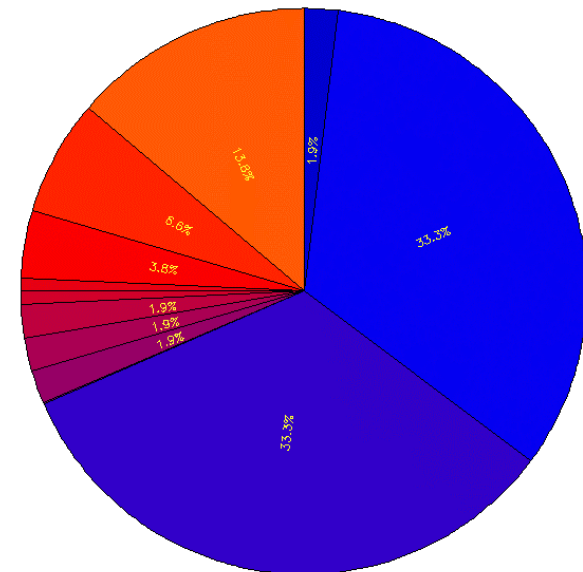
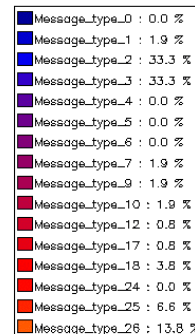
Message type	Maximum update interval time specified in the MOPS	Compliance status to MOPS requirement
1	120 epochs	99.7 %
2,3,4,5+6	6 epochs	99.9 %
2	60 epochs	100%
7	120 epochs	99.7 %
9	120 epochs	99.7 %
10	120 epochs	99.7 %
12	300 epochs	99.9 %
17	300 epochs	100. %
18	300 epochs	100. %
25	120 epochs	99.8 %
26	300 epochs	99.8 %



EGNOS CPF PERFORMANCE ANALYSIS

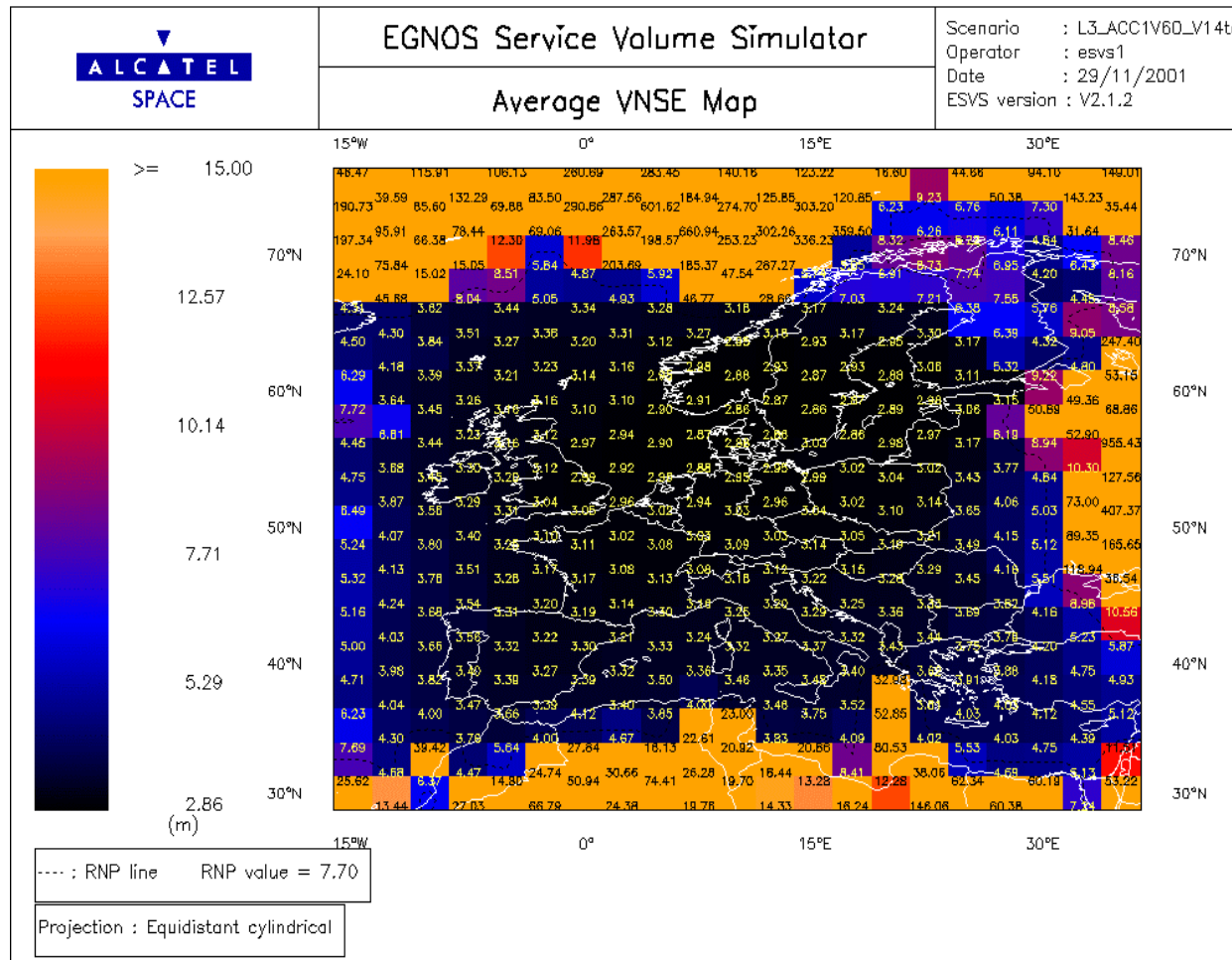
Bandwidth average analysis

Scenario : ACC-01_EETES-SYST5.0.0
Operator : esvs
Date : 22/05/2002
Version : 3.0.1





System CDR Main Outcomes



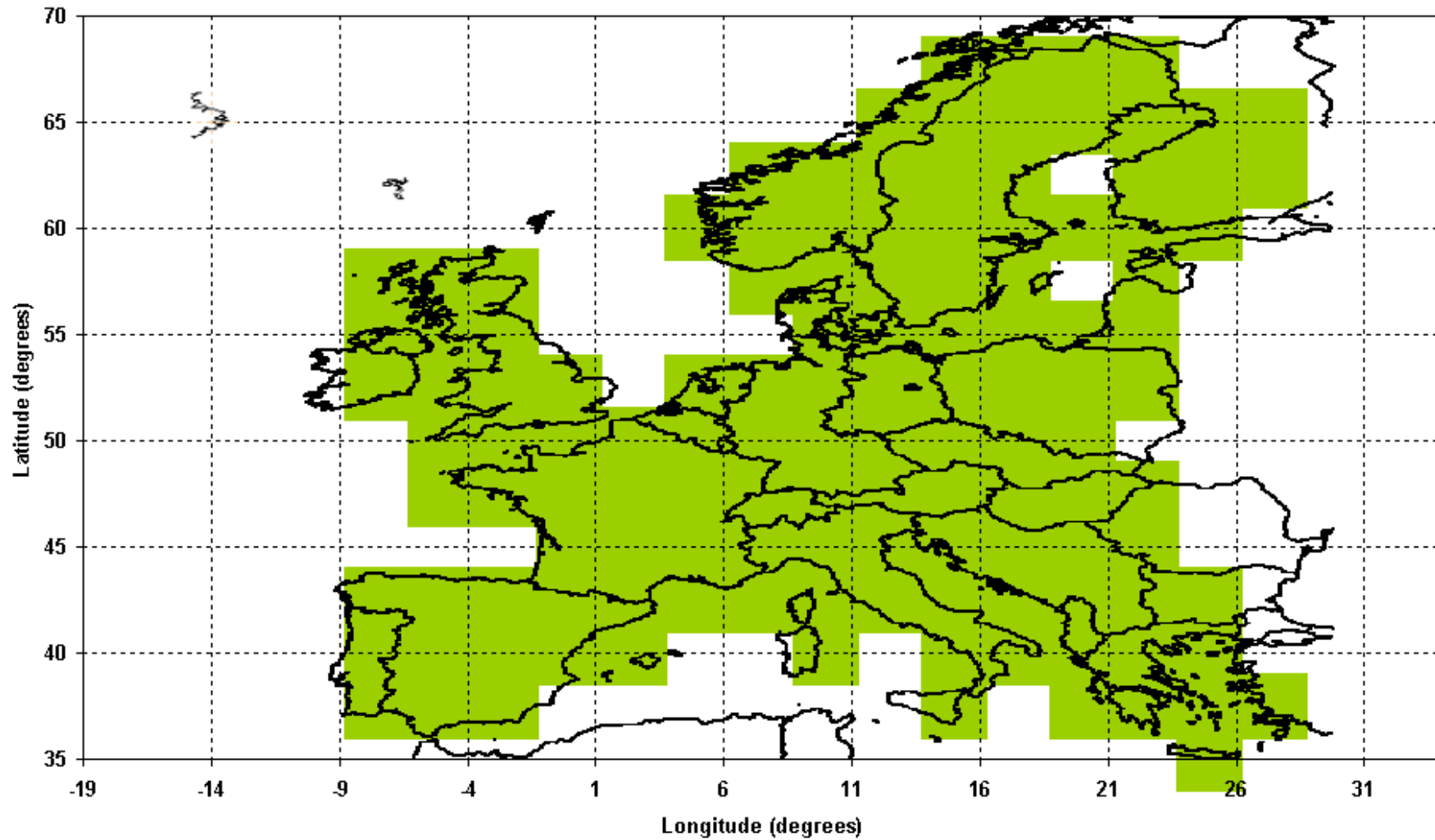
System Accuracy

Horizontal (95%)
 3.5 m (Average)
 2.6 m (Min)

Vertical (95%)
 2.9 m (Average)
 3.9 m (Min)

Good performance on ECAC Land Masses

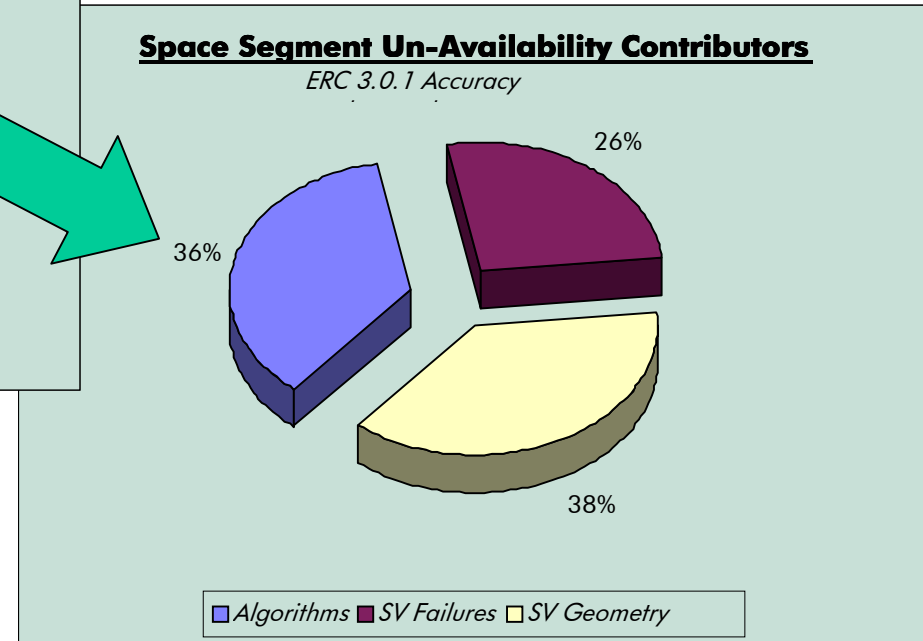
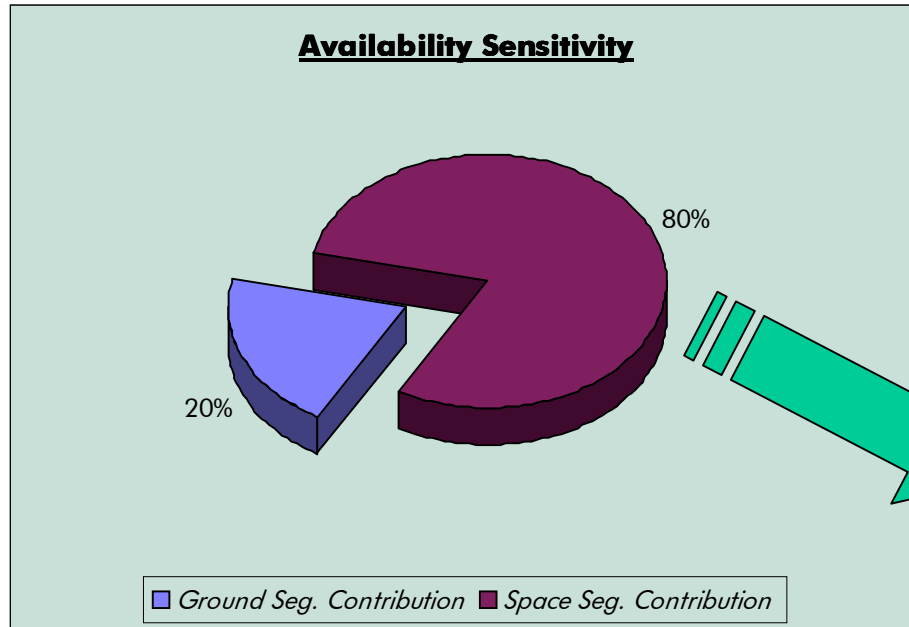
System availability



System CDR Main Outcomes

System availability contributor

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System CDR Main Outcomes

Navigation

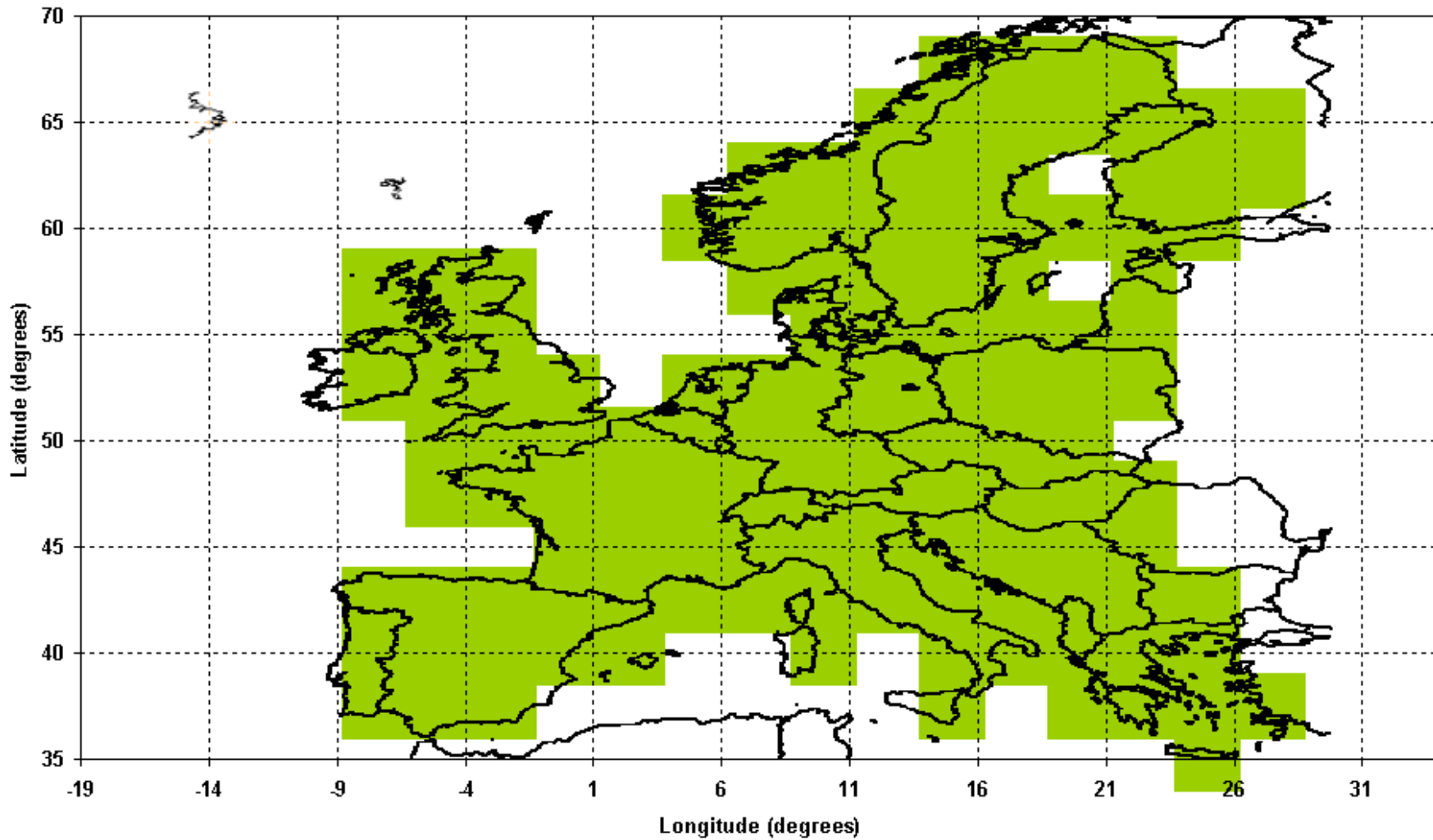
System Integrity

- Integrity Insured in Pseudo-range domain
Mainly Based on CPF results
- After consolidation at System level conclusions are
 - *Integrity Insured on the whole service area
 - *Fault free contribution is negligible with respect to feared events
 - *More than 97% of feared event contribution is due to
 - >Excessive Multipath at RIMS level
 - >Code Carrier Incoherence on the GEO satellite



System CDR Main Outcomes

System Continuity



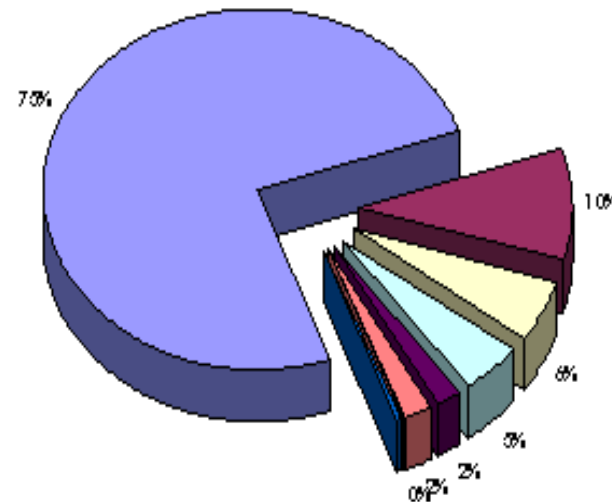
System Continuity contributor

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Fault free represents 17% of the total budget

70% of the feared event budget is due to excessive multipath at RIMS level

Continuity Feared Events





Conclusion

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- The main outcomes of the analysis performed for EGNOS CPF and system Critical Design Review have been presented
- Those results demonstrated during CDR that the proposed EGNOS design was able to fulfil EGNOS PDR commitments
- Integrity risk below specification on the whole ECAC area
 - Continuity and availability compliance areas covers most of the ECAC land masses as required.
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- What shall be also underlined is the methodology used by EGNOS System Engineering team for performance justification.
- This has been recognised as key contributor to a successful CDR completion.